

ARTICLE

Tracking an invasion front with environmental DNA

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Abstract

Data from environmental DNA (eDNA) may revolutionize environmental monitoring and management, providing increased detection sensitivity at reduced cost and survey effort. However, eDNA data are rarely used in decision-making contexts, mainly due to uncertainty around (1) data interpretation and (2) whether and how molecular tools dovetail with existing management efforts. We address these challenges by jointly modeling eDNA detection via qPCR and traditional trap data to estimate the density of invasive European green crab (*Carcinus maenas*), a species for which, historically, baited traps have been used for both detection and control. Our analytical framework simultaneously quantifies uncertainty in both detection methods and provides a robust way of integrating different data streams into management processes. Moreover, the joint model makes clear the marginal information benefit of adding eDNA (or any other) additional data type to an existing monitoring program, offering a path to optimizing sampling efforts for species of management interest. Here, we document green crab eDNA beyond the previously known invasion front and find that the value of eDNA data dramatically increases with low population densities and low traditional sampling effort, as is often the case at leading-edge locations. We also highlight the detection limits of the molecular assay used in this study, as well as scenarios under which eDNA sampling is unlikely to improve existing management efforts.

KEYWORDS

Bayesian modeling, *Carcinus maenas*, environmental DNA, European green crab, false-positive probability, invasion front, invasive species management, N-mixture modeling

INTRODUCTION

Since the first documented use of environmental DNA (eDNA) methods for detecting macro-organisms (Ficetola et al., 2008), the fields of conservation and ecology have seen a wave of eDNA studies, with wide ranging applications across a myriad of ecosystems and target taxa (Beng & Corlett, 2020; Bohmann et al., 2014; Deiner

et al., 2017; Thomsen & Willerslev, 2015). Techniques such as quantitative polymerase chain reaction (qPCR), digital droplet PCR (ddPCR), and high-throughput sequencing (HTS) are increasingly accessible, and can often detect trace amounts of DNA in environmental samples (Jerde, 2019). These molecular techniques yield high-resolution biological information and are particularly useful when traditional monitoring may be

infeasible, labor intensive, or reliant upon diminishing taxonomic expertise (Kelly et al., 2014); in some cases, eDNA assays are more sensitive than traditional sampling methods in detecting rare individuals (Goldberg et al., 2013; Jerde et al., 2011). Together, these attributes make eDNA sampling attractive for detecting rare, cryptic, or elusive aquatic species, and, in particular, invasive species.

Early detection and monitoring are key components of successful invasive species management strategies (Lodge et al., 2006), and detection at early stages of establishment has led to eradications of nascent invasions (Anderson, 2005; Wimbush et al., 2009). However, the effort required to detect a species is inversely proportional to its population size (Hayes et al., 2005), and so invasion fronts present a particular management challenge. Historically, cost-effective management strategies have had to balance high survey costs for small populations and high eradication costs if the survey fails to detect an incipient population in the initial stages of invasion (Lodge et al., 2006). Genetic approaches may better detect rare individuals, and thereby lower costs and improve the sensitivity of surveys for small populations, such as those at invasion fronts (Beauclerc et al., 2019; Harper et al., 2018; Jo et al., 2021; Kuehne et al., 2020; Schütz et al., 2020). However, traditional monitoring methods outperform some eDNA assays (Rose et al., 2019; Ulibarri et al., 2017), underscoring the importance of side-by-side comparisons of detection efficiency.

Despite the advantages of eDNA for early detection of small populations, few examples exist of eDNA methods used to guide decision-making. Notable exceptions include the United Kingdom's acceptance of eDNA qPCR results as evidence for the presence of the protected great crested newt, *Triturus cristatus*; there, developers can be prohibited from developing wetlands where there have been positive eDNA detections (Biggs et al., 2015; Natural England, 2017). Perhaps the best example of management-relevant eDNA surveys focuses on the invasive bighead and silver carps (*Hypophthalmichthys* spp.; often referred to jointly in the United States as “big-headed carp”) (Mize et al., 2019). The US Fish and Wildlife Service (Woldt et al., 2020) and US Department of Agriculture (Carim et al., 2016) have protocols that guide field and laboratory eDNA methods, as well as outline recommendations for sampling plans and schedules to be implemented by regional sampling agencies.

Typically, however, methodological development outpaces systematic plans on how to use DNA evidence to support management decisions. Consequently, managers have been slow to use eDNA-based approaches in decision-making frameworks, (Bohmann et al., 2014;

Darling & Mahon, 2011) due to gaps in understanding the dynamics of eDNA in space and time, as well as the susceptibility of eDNA methods to false-negative detections and false-positive detections (Darling et al., 2021; Goldberg et al., 2016; O'Donnell et al., 2017; Sepulveda, Hutchins, et al., 2020). Although all sampling methods have potential errors, there are many mechanisms for eDNA methods to indicate a false presence; the fear of a false-positive detection is cited as the primary obstacle to adopting eDNA-based methods in species monitoring (Jerde, 2019). Even though emerging statistical approaches have aimed to estimate the probability of false-positive error (Griffin et al., 2019; Guillera-Aroita et al., 2017), clearly communicating of the meaning of false-positive errors—and more generally, uncertainty surrounding the meaning of results—to managers and the public remains challenging (Darling et al., 2021).

Previous reviews highlight the “potential” of eDNA methods to dramatically improve biodiversity assessments and targeted detection of species of concern, as well as the “potential” for unreliability and augmentation of existing uncertainty in environmental management and assessment (Beng & Corlett, 2020; Bohmann et al., 2014; Darling & Mahon, 2011; Yoccoz, 2012). Moving from evaluating the potential value of eDNA data to the practical value of eDNA data requires quantitative and meaningful interpretations of the available data (Cristescu & Hebert, 2018; Lacoursière-Roussel & Deiner, 2021), as well as demonstrating the ways in which eDNA does—or does not—complement existing management strategies.

Recent work has significantly advanced eDNA data interpretation by extending site-occupancy modeling methods to estimate species presence and absence using eDNA data (Schmidt et al., 2013). Such models account for imperfect detection when inferring species occupancy and can overcome bias introduced by false-negative and false-positive detections (Hunter et al., 2015; Lahoz-Monfort et al., 2016; Schmelzle & Kinziger, 2016). Occupancy estimation has become a standard method for modeling species dynamics, monitoring species trends, and informing management (MacKenzie et al., 2002, 2003). The approach has been adapted to accommodate violations of model assumptions (Lele et al., 2012) and survey scenarios in which multiple types of observational error occur (McClintock et al., 2010; Miller et al., 2011).

Occupancy models suggest that there are two classes of sites, those that are occupied and those that are not, and these models assume no unmodeled heterogeneity among sites in the probability of detecting a species at sites where it occurs (Altwegg & Nichols, 2019; Royle & Nichols, 2003). In reality, variation in local abundance of the species among sites is one important factor that can

induce heterogeneity in detection probability with ecological or genetic methods (Royle & Dorazio, 2008), resulting in low estimates of occupancy probability at sites where a species is present, but rare. Even for a relatively sensitive assay, a low molecular detection rate can therefore reflect low abundance, rather than low probability of occupancy.

Royle and Nichols (2003) aimed to overcome this limitation by describing a modeling approach that links heterogeneity in abundance to heterogeneity in detection probability, estimating abundance from repeated observations of a species. This heterogeneous detection probability model provides a framework for estimating species density based on abundance-induced variation in detection probability with eDNA methods (Royle & Nichols, 2003). Building on this framework, we jointly modeled observations from both traditional and eDNA monitoring methods to estimate local species density. The joint model aided management decisions by informing the interpretation of molecular detections, the most appropriate use of eDNA sampling efforts, and the relative sensitivities of molecular and traditional sampling methods.

We applied the joint model to eDNA detection data of European green crab, *Carcinus maenas*, in Washington State, USA. The green crab causes massive ecological and economic damage in its invaded range; for example, the species has caused the collapse of the soft-shell clam industry in Maine (Glude, 1955; Tan & Beal, 2015). The green crab was first detected in Washington waters in 1998, after warm El Niño–Southern Oscillation (ENSO) currents spread larvae of California populations up to British Columbia, Canada (Behrens Yamada & Hunt, 2000), and the species is now classified as a deleterious species in Washington State because of perceived risks to coastal resources (Grason et al., 2018). The Washington Department of Fish and Wildlife (WDFW), the United States Fish and Wildlife Service (USFWS), Washington Sea Grant, several sovereign tribal nations, and other concerned citizens have subsequently coordinated to monitor and manage green crab along the nearly 3000 km of Washington’s inland shoreline.

Traditionally, crab traps have provided much of the quantitative information about the position of the green crab’s invasion front in Washington, and the State is investing heavily in deploying traps throughout probable invasion pathways. Here, we coupled this existing data set with qPCR data, using a recently developed assay for green crab (Roux et al., 2020) derived from water samples collected throughout the region. We combined these data streams to estimate the density of green crab across the study sites using the joint model, and we highlight changes in the precision of these estimates in the joint model vs. a model that uses only traditional trapping

data; the difference between the two is the marginal information benefit of eDNA for this particular management purpose. This modeling framework offers a path to improve interpretation of eDNA data, as well as to identify the scenarios under which eDNA sampling will most likely improve existing management efforts.

METHODS

Joint model description

We modeled traditional trap data and eDNA qPCR detections jointly, linking the two through a shared species density at each sampling site (Data S1).

Traditional monitoring methods—here, trapping—relate repeated capture rates to an underlying species density. As previous work on analyzing green crab capture in traps found patchy distribution, with significant local-scale variation within a site (Bergshoeff et al., 2019), we modeled the capture process using a negative binomial distribution to account for overdispersion. We also conducted a leave-one-out cross-validation approach to evaluate the relative predictive accuracy of distribution choices for modeling the capture process based on the observed data (Vehtari et al., 2017) (Appendix S1: Data S2). The observed count, Y , of a species at site i and trap sample k is drawn from a negative binomial distribution with a mean species density, μ_i , and an overdispersion parameter, Φ (Equation 1):

$$Y_{i,k} \sim \text{NegBinomial}(\mu_i, \Phi) \quad (1)$$

Guided by the principle that the probability of detection with qPCR increases as the underlying species density increases, we describe the probability of a true molecular detection, p_{11} , at site i as a saturating function of species density, μ_i , and scaling coefficient, β (Equation 2):

$$p_{11,i} = \frac{\mu_i}{\mu_i + \beta} \quad (2)$$

Recognizing the susceptibility of eDNA methods to false-positive errors (Roussel et al., 2015; Sepulveda, Nelson, et al., 2020), we incorporated a false-positive probability, p_{10} , that represented two sources of false-positive detections: (1) the presence of target DNA in the sample, but absence of target organism at the associated site, arising from processes such as laboratory contamination or transportation of target cells from far away locations, and (2) absence of target DNA in the sample but a positive molecular detection, arising from non-specific amplification. The false-positive probability, p_{10} , contributed to the overall molecular

detection probability, p , at site i (Equation 3; p is bounded between 0 and 1):

$$P_i = P_{10} + P_{11,i} \quad (3)$$

We estimate these parameters through repeated molecular observations at each site using a species-specific quantitative PCR (qPCR) assay (Roux et al., 2020). Many applications of qPCR are interpreted as molecular binary indicators of detection (1) or nondetection (0) (Guillera-Arroita et al., 2017; Orzechowski et al., 2019; Schmidt et al., 2013), and the binomial distribution is suitable for modeling “successes” in a given number of trials (Hobbs & Hooten, 2015). The number of positive qPCR detections, K , out of the number of trials, N , in water sample j at site i is drawn from a binomial distribution, with a probability of success on a single trial, p_i (Equation 4). Due to the hierarchical qPCR data structure, in which qPCR triplicates are nested within water bottles within sites, we also provide a hierarchical version of the model that accounts for membership of qPCR replicates within nested groups (Appendix S2, Data S3). We present a simpler model here:

$$K_{ij} \sim \text{Binomial}(N_{ij}, p_i) \quad (4)$$

We implemented the model in a Bayesian framework, in which the posterior probability of the model parameters (given observed data) is product of the individual likelihood functions at site i (i in 1... n), water sample j (j in 1... m), and trap sample k (k in 1... q), as well as the prior probabilities (Equation 5). A gamma distribution was used as the prior distribution for parameters μ_i , Φ , and β because of its suitability for continuous, non-negative random variables. These prior distributions allowed us to incorporate existing information into the analysis and help to make the parameters identifiable:

$$\begin{aligned} [\mu_i, \phi, \beta, p_{10}] \propto & \prod_{i=1}^n \prod_{j=1}^m \prod_{k=1}^q \text{NegBinomial}(Y_{ik} | \mu_i, \phi) \\ & \times \text{Binomial}(N_{ij}, K_{ij} | p_{10}, \mu_i, \beta) \\ & \times \text{Gamma}(\mu_i | \alpha_\mu, \beta_\mu) \times \text{Gamma}(\phi | \alpha_\phi, \beta_\phi) \\ & \times \text{Normal}(p_{10} | \mu_{p_{10}}, \sigma^2_{p_{10}}) \\ & \times \text{Gamma}(\beta | \alpha_\beta, \beta_\beta) \end{aligned} \quad (5)$$

We specified the model within Stan, a probabilistic programming language written in C++ that implements full Bayesian statistical inference using Markov chain Monte Carlo, and used the package *rstan* (version 2.21.2) as an interface to the R (version 4.1.1) software environment (Carpenter et al., 2017; Guo et al., 2020; R Development Core Team, 2021).

Green crab eDNA data collection

eDNA field sampling

In total, 20 sites with varying known presence and abundance of green crab were chosen for eDNA sampling (Figure 1; Appendix S3: Figure S1) and, given the time scale of the sampling effort, all sites were distinct with relation to green crab movement. At each site we collected five 500-ml surface water samples at 1–5 m apart. All sampling equipment was soaked in 10% bleach among sites and thoroughly rinsed in deionized water to prevent cross-contamination. Water samples were placed on ice and vacuum filtered onto a cellulose acetate filter (47 mm diameter, 0.45 μm pore size) within 4 h of collection, except for samples from the KVI site, where samples were stored at 4°C and filtered 24 h after collection due to vacuum equipment malfunction. Filters were preserved in 900 μl of Longmire buffer (Longmire et al., 1997; Renshaw et al., 2015) and stored at -80°C for 1–3 weeks before DNA extraction. In total, 100 eDNA water samples were collected.

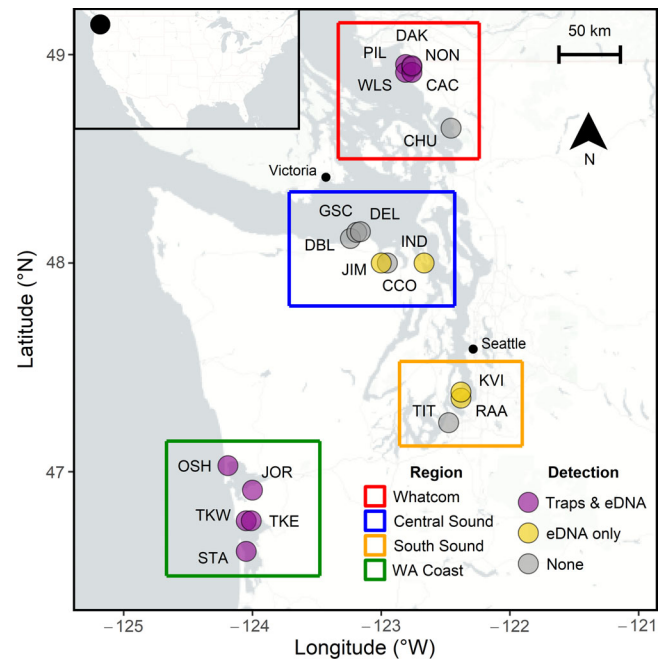


FIGURE 1 Environmental DNA and trapping detections of green crab over the sampling period. Purple dots indicate sites where green crabs were trapped and eDNA samples yielded at least one positive detection. Yellow dots indicate sites where no green crabs were trapped and eDNA samples yielded at least one positive detection. Gray dots indicate sites where no green crabs were trapped and eDNA samples yielded no positive detections. Sampled sites are labeled with the site ID and polygons are colored by region. The inset map indicates study the location in the context of the United States. A key for site abbreviations is included in Appendix S4: Table S2

eDNA sample processing

We extracted DNA from filters using a phenol:chloroform:isoamyl alcohol protocol modified from (Renshaw et al., 2015) and described in (Gallego et al., 2020). One negative control (900 μ l of Longmire buffer) was extracted during each set of DNA extractions ($n = 3$ in total). We quantified DNA purity on a spectrophotometer (NanoDrop, Thermo Scientific, Inc.) and DNA concentration on a fluorometer (Qubit, Invitrogen, Inc.) to determine DNA extraction success.

Each eDNA extract was amplified by qPCR using a *C. maenas*-specific assay developed by Roux et al. (2020) that targeted a 148-bp fragment of the cytochrome *c* oxidase 1 (CO1) region. Three qPCR replicates were run for each eDNA extract in 25- μ l reactions following the protocol of Roux et al. (2020), but we modified the protocol to use TaqPath™ ProAmp™ Master Mix due to its relatively high tolerance of inhibitors (Applied Biosystems, A30865). Three negative PCR controls containing 2 μ l of molecular grade water were included in each reaction, and each extraction negative control was run in triplicate. All qPCR reactions were performed on the Applied Biosystems StepOnePlus Real-Time PCR System and analyzed with StepOne Software v2.3. Any DNA template passing the fluorescence threshold in fewer than 38 cycles was considered a positive amplification, as 38 Ct is the average Ct value corresponding to the assay's limit of detection with a 50% chance of detection (Roux et al., 2020). The identity of 13 qPCR products from four sites was confirmed through unidirectional Sanger sequencing with the forward primer; all sequences were unambiguously *C. maenas*, and no other crabs from the same taxonomic family are present in the region (Appendix S4: Table S1).

In addition to the 20 sites sampled concurrently with trapping efforts, eDNA samples from seven sites in Skagit Bay, WA were analyzed using the same sampling, DNA extraction, and qPCR procedures (Appendix S4: Table S2). These sites were characterized as unsuitable for green crab based on expert opinion and were included as sites of unambiguous crab absence to inform the prior detection on the estimated probability of a false-positive molecular detection (p_{10}). Four water samples at each of the seven sites were processed at an independent laboratory facility (NOAA Northwest Fisheries Science Center), where each water sample underwent triplicate qPCR reactions, alongside nine no-template negative controls and three field blank negative controls.

Inhibition testing

To ensure that negative qPCR detections were not systematically due to PCR inhibition, we measured potential

inhibition occurrence by analyzing the quantification threshold (Ct) deviation of a spiked internal positive control. A synthetic (gBlock) positive control was spiked into samples with no positive amplifications (Integrated DNA Technologies, Inc.). The double-stranded 200-bp gBlock oligonucleotide contained a green crab-specific primer and probe sequences, with three modified bases between the forward primer and probe and two modified bases between the probe and reverse primer to identify contamination at the amplification step. For sites where all eDNA replicates previously tested negative for green crab, we subsequently tested one eDNA sample per site for inhibition. For sites where some but not all eDNA replicates tested negative for green crab, each previously negative eDNA sample was tested for inhibition. Each qPCR reaction used 1 μ l of environmental DNA extract and 1 μ l of the gBlock positive control at a final reaction concentration of 0.20 gBlock copies/ μ l. Three qPCR replicates containing 1 μ l of the gBlock positive control (without eDNA extract) at a final reaction concentration of 0.20 copies/ μ l were also included in the reaction. Inhibition occurrence was measured as the difference in Ct, Δ Ct, between the Ct value of the spiked eDNA sample and the mean of the three positive gBlock controls ($C_{t_{\text{sample}}} - C_{t_{\text{control}}}$) (Volkman et al., 2007). We conservatively considered a Δ Ct greater than two cycles to be evidence of inhibition, considering that three cycles—as is common in the literature (Hinlo et al., 2017)—is almost one order of magnitude difference in concentration in an efficient reaction. Each DNA sample underwent 1–3 passes through a OneStep PCR Inhibitor Removal spin column (Zymo Research Corp.) until inhibition occurrence was not detected (Appendix S4: Table S3).

Green crab trapping data

The Washington State Department of Fish and Wildlife, Washington Sea Grant, US Department of Fish and Wildlife, and Jamestown S'Klallam Tribe provided data from baited traps from a larger green crab monitoring program. Traps were set for an overnight soak and collected within 24 h of placement; any trapped green crabs were counted and subsequently removed from the system. Trap types included in the data set were Gee-brand galvanized steel minnow traps (5.08 cm opening, 0.635 cm mesh) and the square Fukui fish traps (1.27 cm mesh), which have similar catchability for green crab and mechanisms of trapping.

The sampling sites varied with respect to known green crab presence, abundance, and trapping effort (Appendix S3: Figure S1). Trapping effort ranged from

three to 420 traps set over the selected trapping period, and water samples were collected 2 weeks before or after trap collection, with the exception of the Stackpole site (STA) (Appendix S3: Figure S2). At STA, only three traps were set during the sampling period, and no green crabs were recovered. To reflect the relatively high density of green crab determined through previous, greater trapping efforts, trapping data at STA collected at 8 weeks before eDNA sampling were included in the data set (Appendix S3: Figure S2). Despite trapped crabs being removed from the system, our analysis assumed that these removals did not substantially change the relative densities of green crab at the sampled sites over the sampling period (Appendix S3: Figure S2).

Joint model application: Green crab density estimates

We fitted the joint model to the qPCR and trap observations using weakly informative priors for all parameters except for the false-positive rate of detection, p_{10} , for which we used an informative prior from the negative control data listed in Roux et al. (2020) and the eDNA samples from sites characterized a priori as unsuitable for green crab. We set the p_{10} prior at $\text{beta}(1,28)$, such that the false-positive detection probability was likely to be less than 0.036 ($P[p_{10} < 0.036] = 0.64$). For ease of model-fitting in *Stan*, we moved p_{10} to a log scale, and used moment matching to convert the beta prior into a lognormal distribution (Hobbs & Hooten, 2015). To reflect prior knowledge of the presence of green crab at each site beyond the information provided in the trap data, different hyperparameters were used for the prior distributions for μ based on green crab recovery at the sampled sites from 2017–2021 (Appendix S4: Table S2). The prior distribution for μ at sites with a history of trapped green crab was $\mu_{\text{crab}} \sim \text{gamma}(0.25, 0.25)$, and the prior distribution for μ at sites without a history of trapped green crab was $\mu_{\text{nocrab}} \sim \text{gamma}(0.05, 0.05)$. Priors for the other model parameters were as follows: $\beta \sim \text{gamma}(2, 1)$ and $\Phi \sim \text{gamma}(0.25, 0.25)$.

We ran the joint model via *rstan* with a step size of 0.5 and 4 chains with 500 warm-up and 2500 sampling iterations per chain, and we checked for model convergence through the *R-hat* convergence diagnostic and by visually examining the resulting autocorrelation plots and chain mixture in the trace plots using the package *shinystan* (Gabry et al., 2018). For comparison, we ran a trap-only model (Equation 1) in the same way.

As crab density decreases, the probability of true-positive molecular detection decreases and, at very low

crab densities, the probability of a false-positive detection, p_{10} , is higher than the associated true-positive detection, p_{11} . Here, we defined the crab density threshold at which a detection is equally likely to be true or false ($p_{10} = p_{11}$) as the critical crab density, μ_{critical} . This value was calculated using the model's posterior distributions of estimated parameters, p_{10} and β , and the relationship between μ and p_{11} defined in Equation 2.

Robustness assessments

A sensitivity analysis was conducted to ascertain the sensitivity of the model's inferences to the specification of the false-positive probability, p_{10} , prior distribution. The joint model was refitted using a set value for p_{10} less than a range of values (0.005–0.055), and all other parameters (β , Φ , μ_i) were estimated. All refitted models were run with a step size of 0.5 and four chains with 500 warm-up and 2500 sampling iterations per chain and were checked for model convergence.

We also examined the effect that priors had on our inferences by conducting the data-cloning procedure described by Lele et al. using the package *dclone* (version 2.3-0) (Data S1) (Lele et al., 2007; Solymos, 2019). We replicated the qPCR and trapping data sets ($n = 10$) for each sampled site and used these copies as data input in our model to swamp the posterior distribution, which subsequently minimized the influence of the prior distributions and yields estimator outputs that are asymptotically equivalent to maximum likelihood estimators (Lele et al., 2007). We evaluated the influence of the prior distributions on our model's inferences by comparing data cloning parameter estimates to our Bayesian parameter estimates.

We then compared our model's inferences to parameter estimates derived from an occupancy modeling framework. We estimated occupancy parameters using the qPCR detection data and the R package, *msocc* (version 1.1.0), which implements a Gibbs sampler to fit Bayesian multiscale occupancy models (Data S1) (Stratton et al., 2020). The occupancy model was run with 11,000 total MCMC iterations (1000 burn-in iterations), and site-specific sample-level probabilities of occupancy, θ_i , and site-specific replicate-level probabilities of occupancy, p_i , were estimated. Replicate-level probabilities of occupancy, $p_{i,\text{occupancy}}$, were compared with the overall probabilities of molecular detection, $p_{i,\text{joint}}$, from the joint model, and a linear regression was fitted to model the relationship between $p_{i,\text{occupancy}}$ and $p_{i,\text{joint}}$ using the *lm()* function in R.

Evaluation of eDNA data's marginal benefit

As information increases, uncertainty decreases. We therefore considered a reduction in uncertainty around green crab density estimates as a measure of the marginal value of eDNA data, relative to the baseline information contained in trap data alone. We quantified precision in the estimates of green crab density, μ_i , using a coefficient of variation (CV; the standard deviation of the parameter estimate divided by the mean), to facilitate comparisons of variability across green crab densities of differing orders of magnitude (Abdi, 2010). We calculated the change in precision (ΔCV) in the parameter estimates in the joint model vs. trap-only model as $CV_{\text{trap}} - CV_{\text{joint}}$, and we analyzed this change in precision as a function of trapping effort. The qPCR effort remained constant throughout data collection. We captured the resulting exponential trend line in the relationship between ΔCV and trapping effort using the method of least squares.

To evaluate the sensitivity of eDNA vs. trap sampling, we estimated the sampling effort necessary to detect a green crab with 90% confidence. A detection refers to either capturing at least one green crab in a trap or producing at least one true-positive qPCR amplification. For trap sampling, we calculated the minimum number of traps necessary to be 90% confident that at least one crab would be caught (Equation 1; given a non-zero expected number of crabs/trap, μ , and the model's median estimate for dispersion parameter, Φ). For eDNA sampling, we defined effort as the number of unique water samples, each having triplicate qPCR. We calculated the minimum number of water samples, E , necessary to detect the true presence of crab with at least 90% confidence as $\text{binomial}(E \times N, p_{11})$, in which $N = 3$. p_{11} was defined as in Equation 2 and depends upon the underlying true number of crabs/trap, μ , and the model's median estimate for parameter β . Both sampling type analyses were conducted under a range of crab densities, from median $\mu_{\text{critical}} - 3.0$ crabs/trap.

Simulation study

We simulated the precision and accuracy of green crab density estimates as a function of sampling strategy, given a range of green crab trapping efforts and true species densities. Both qPCR data and green crab trap count data were simulated for each of nine green crab densities (0, 0.02, 0.05, 0.1, 0.15, 0.25, 0.5, 1, 3 crabs/trap [μ_{sim}]) and 11 trapping efforts (3, 4, 5, 7, 10, 12, 15, 20, 30, 40, 60 traps), for a total of 99 scenarios. The eDNA sampling effort was held constant at five biological replicates and three technical replicates for all simulated scenarios. Each scenario made up a

different site, i_{sim} , in the overall simulated data set, and we simulated each data set 50 times to capture stochasticity. These scenarios represented the range of green crab densities and trapping efforts observed in this study.

We then used the simulated data sets to estimate the underlying green crab density, μ_{sim} , at each simulated site, i_{sim} , with both the joint and trap-only models. Only parameter μ_{sim} for each simulated site was estimated by the two models, and parameters p_{10} , β , and Φ were set at the joint model's median estimate derived from collected data. A prior distribution for μ of $\text{gamma}(0.05, 0.05)$ was used at all simulated sites, and each model was run with four chains of 500 warm-up iterations and 2500 sampling iterations (Data S4). We calculated the mean change in precision (ΔCV) of the 50 simulation replicates at each simulated site to determine the effect of trapping effort and underlying crab density on changes in estimated crab density precision. We calculated model accuracy for each simulation scenario as the proportion of simulation replicates that yielded a 90% credibility interval containing the true density, μ_{sim} .

RESULTS

Green crab genetic and traditional monitoring data collection

We detected at least one positive amplification at 13 sites, (1–15 amplifications out of 15 total qPCR replicates per site; five biological replicates \times three technical replicates per site; Appendix S4: Table S3). In a total of 1274 trap observations (3–420 traps set over the sampling period; Appendix S3: Figure S2), green crabs were trapped at nine of the 20 sampled sites over the sampling period (mean crabs/trap 0–6.04). All nine of these sites had positive eDNA detections, whereas four additional sites yielded at least one positive eDNA detection when no green crabs were trapped over the sampling period (Figure 1). At two of these four additional sites, green crabs were recovered in traps over a longer time horizon (2017–2021) than the extent of the sampling period (Appendix S4: Table S2). All samples collected at sites characterized as unsuitable for green crab produced negative qPCR results, and all no-template (negative) qPCR controls and DNA extraction blanks produced negative qPCR results.

Detection of green crab eDNA beyond known invasion front

Both the joint and trap-only models yielded an R -hat of one for all estimated parameters and produced well

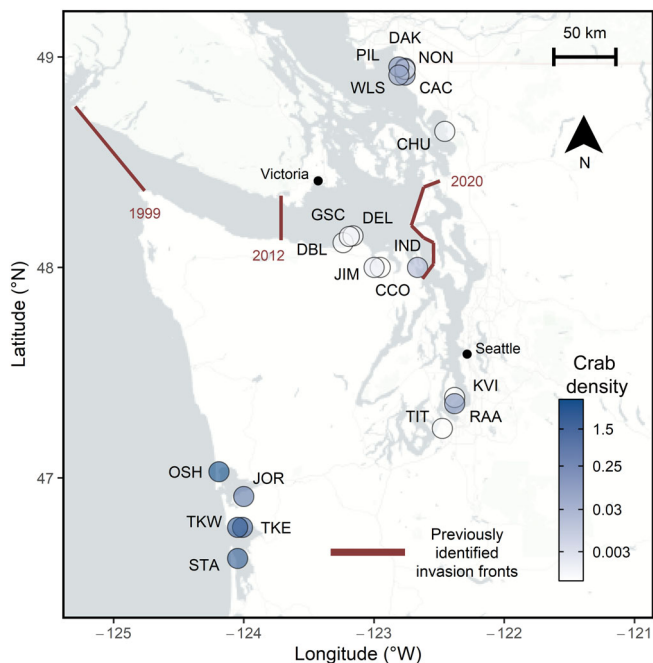


FIGURE 2 Median of the joint model's posterior distributions of estimated green crab density at the 20 sampled sites. Colors indicate the median green crab density (crabs/trap) estimated by the joint model. The red lines designate previously identified invasion fronts in 1999, 2012, and 2020. A key for site abbreviations is included in Appendix S4: Table S2

mixed chains and low serial autocorrelation, indicating model convergence. The median calculated critical crab density, μ_{critical} , or threshold at which the true-positive probability of molecular detection equals the false-positive probability of molecular detection ($p_{10} = p_{11}$) was 0.056 crabs/trap (0.010, 0.12 90%CrI).

The joint model estimated a relatively high green crab density in a location beyond the previously known invasion front (Figure 2) and provided well constrained estimates of parameter values, including the false-positive rate ($p_{10} = 0.022$, [0.0095, 0.048 90%CrI]; Table 1). Green crab eDNA was detected on Vashon Island, more than 60 km south of the southernmost visual observations of the species (Figure 2). The median estimated green crab density at the Raab's Lagoon (RAA) site on Vashon Island was 0.16 crabs/trap (4.0e-61, 0.61 90%CrI) (Figure 3, Appendix S4: Table S4). The probability that the green crab density at Raab's Lagoon (RAA) was greater than the median μ_{critical} , 0.056 crabs/trap, was 0.64. This relatively high density of green crab was similar to density estimates at sites in the Whatcom region, where historically green crabs have been recovered in traps under high trapping efforts (estimated densities 0.065–0.59 crabs/trap; Appendix S4: Table S4).

The concurrent eDNA and trap sampling meaningfully constrained the lower limit of eDNA sampling's

TABLE 1 Parameters estimated by the joint model, with the median and 90% credibility intervals (highest density interval calculation) of the 10,000 sampling iterations

Parameter	Median estimate	90% credibility interval
Φ	0.94	0.72, 1.2
β	2.5	1.6, 3.5
p_{10}	0.022	0.0095, 0.048

Note: Φ is the overdispersion parameter in the negative binomial distribution of species counts (Equation 1), β is the coefficient relating species density to true-positive molecular detection probability (Equation 2), and p_{10} is the false-positive molecular detection probability (Equation 3).

sensitivity relative to trap sampling. At Graveyard Spit Channel, the eDNA samples yielded no positive molecular detections, and no green crabs were trapped out of the 86 traps set during the sampling period. The estimated median green crab density at this site was low (0.00049 crabs/trap; 2.4e-18, 0.0079 90%CrI). However, in 2020, 1369 traps were set, and three green crabs were recovered (0.002 crabs/trap) and, in April 2021, three more crabs were recovered at this site, indicating that it was nearly certain that crabs were present in the channel during the time of sampling, but not detected by eDNA sampling; this appears to be a false-negative result.

Three sampled sites—Indian Island (IND), Jimmycomelately creek (JIM), and KVI Beach (KVI)—yielded one positive molecular detection, yet their median estimated crab densities were below μ_{critical} , or the crab density at which the false-positive probability of detection equaled the true-positive probability of detection, given the estimated crab density (Appendix S4: Table S4). The probability that the crab densities were greater than the median μ_{critical} was 0.35, 0.017, and 0.096 for IND, JIM, and KVI, respectively. Given the estimated crab densities at these sites, these molecular detections were as likely to be a false-positive detection than a true-positive detection. One sampled site, JIM, in the Central Sound produced one positive qPCR detection, yet the 43 traps set over the sampling period recovered zero green crab individuals. During 2020, no green crabs were recovered in traps, but in July 2021, 9 months after eDNA sampling, five adult green crabs were recovered in a neighboring channel to the site sampled for eDNA.

Robustness assessments

The model refitting procedure using set values for the false-positive probability p_{10} ($p_{10} = 0.05$ –0.55) indicated that some parameter estimates were sensitive to p_{10} . Among the four sites with at least one positive

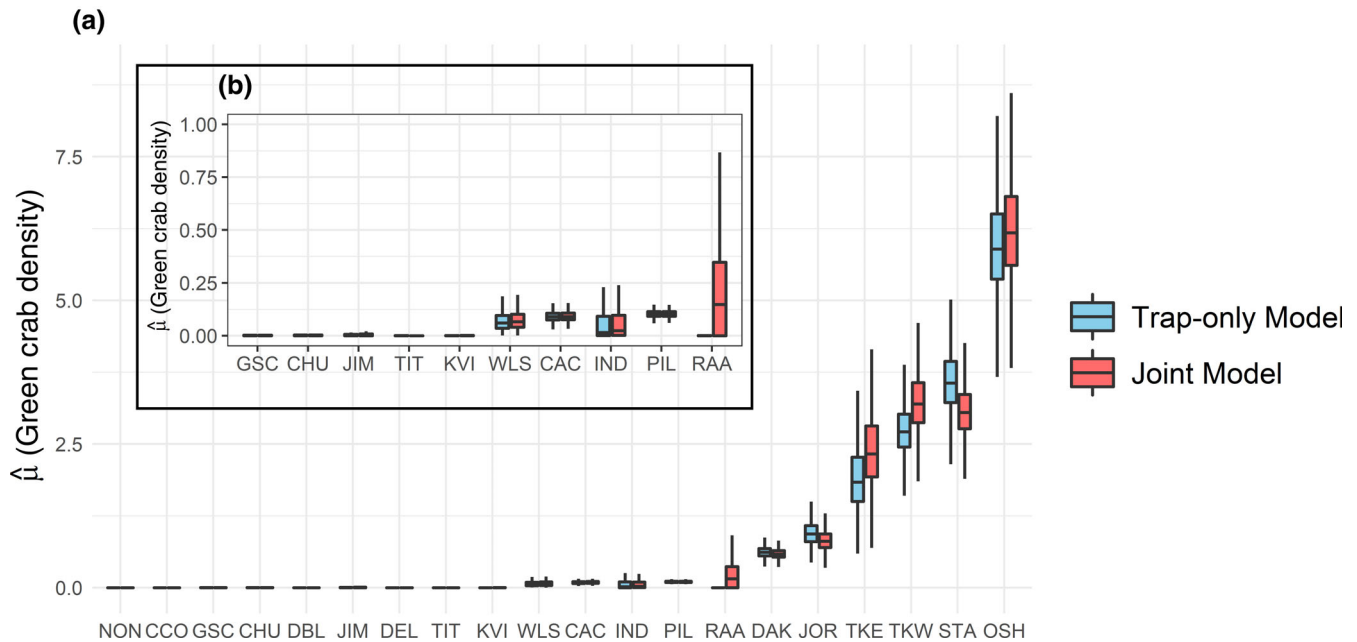


FIGURE 3 (a) Posterior distributions of estimated green crab density at each of the 20 sampled sites. Red boxplots are the estimated densities using the joint model, incorporating both trapping and eDNA information, and blue boxplots are the estimated densities using the trap-only model, using only trapping information. The lower and upper hinges correspond to the posterior data’s first and third quartiles. (b) Subset of sites where the joint model’s estimated median green crab density ranges between 4.4×10^{-8} and 0.1 crabs/trap. A key for site abbreviations is included in Appendix S4: Table S2

eDNA detection and no crabs trapped over the sampling period (RAA, IND, KVI, JIM), all four μ estimates were sensitive to the value set for p_{10} during model refitting (Appendix S3: Figure S3a,c). At these sites, lower values of p_{10} yielded higher estimates of μ , and this effect was strongest for sites with a low trapping effort (RAA, IND, KVI) (Appendix S3: Figure S3a,c). All other μ estimates at the remaining 16 sites were insensitive to the set value of p_{10} (Appendix S3: Figure S3d). As expected with a lower p_{10} and subsequently a more sensitive assay, lower set values of p_{10} yielded lower estimates of the scaling parameter, β (Appendix S3: Figure S3b).

For the data cloning procedure, all parameter maximum likelihood estimates were within the 90% credibility intervals estimated by the Bayesian model. The median maximum likelihood estimates of μ (μ_{MLE}) were nearly identical to the median Bayesian estimates of μ (μ_{Bayes}), although the median μ_{MLE} was slightly higher than the median μ_{Bayes} at sites with a lower trapping effort (Appendix S3: Figure S4). The median maximum likelihood estimate of Φ was 0.96, which was nearly identical to the median Bayesian estimate of Φ (0.94) (Table 1). The median maximum likelihood estimate of β was 2.3, and the median maximum likelihood estimate of p_{10} was 0.012. Both median MLE estimates of β and p_{10} were lower than their respective median Bayesian parameter estimates, yet the median

MLE estimates were inside the Bayesian 90% credibility intervals (Table 1).

The joint model’s inferences were also consistent with parameters estimated from an occupancy modeling framework. The site-specific replicate-level probabilities of occupancy, $p_{i,occupancy}$, were consistent with site-specific molecular probabilities of detection, $p_{i,joint}$, from the joint model (Appendix S3: Figure S5). A linear regression between the two parameters indicated that 71.8% of variation in $p_{i,occupancy}$ was explained by $p_{i,joint}$ (F-statistic: 45.9, p -value: 2.40×10^{-6}).

Quantifying uncertainty to find the value of eDNA information

At sites with lower trapping effort, adding eDNA data narrowed the credibility intervals for estimated crab density, relative to a model using only trapping data. Moreover, the leading edge of an invasion, such as the Central and South Sound, often featured low densities of the invading species. Here, the combination of eDNA and trapping data vastly reduced the uncertainty associated with low trapping effort in these cases (Figure 4). As the trapping effort decreased, the marginal benefit (ΔCV) of eDNA data increased exponentially (Figure 4), dramatically increasing the precision of green crab density estimates at sites along the invasion front and at sites characterized by low trapping efforts.

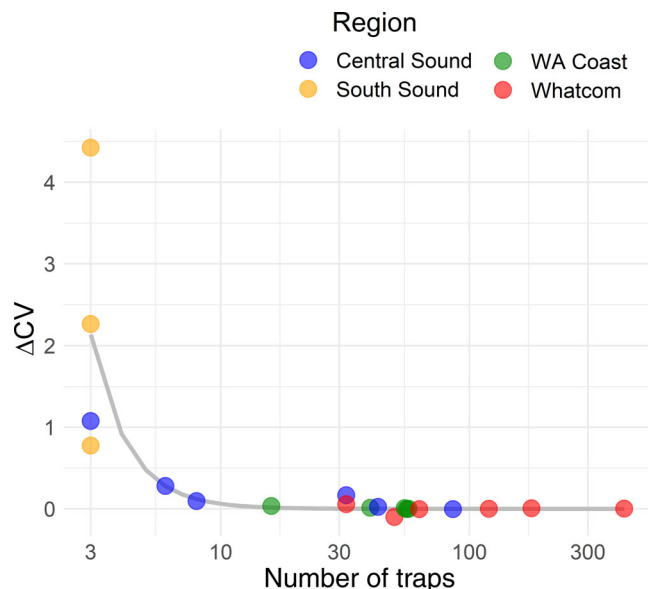


FIGURE 4 Difference in the coefficient of variation (ΔCV) in the posterior distributions of the estimated green crab densities between a model using only trapping information (trap-only model) and a model using both trapping and eDNA information (joint model). The gray line designates the best-fit trend line, $\Delta CV = 54 \times \exp(-2.94 \times \log[\text{traps}])$

To identify the relative sensitivities of the two sampling methods, we determined the sampling effort necessary to detect a green crab with 90% confidence, given the joint model’s estimated parameters. This sampling effort was calculated for a range of simulated crab densities, from 0.056 crabs/trap (median estimated μ_{critical}) to 3.0 crabs/trap. The detection sensitivity—the probability of capturing at least one crab in one trap or the probability of one true-positive qPCR amplification in triplicate trials—was higher for eDNA sampling than for trap sampling, suggesting that the information provided by one water bottle is slightly greater than the information provided by one trap (Figure 5).

eDNA’s greatest marginal benefit at low species densities and trapping effort

Simulations further indicated that the marginal benefit of eDNA data, measured as ΔCV , increased as trapping effort decreased for all simulated densities of green crab (Figure 6). Importantly, these information benefits tended to be highest at true crab densities (μ_{sim}) in the range 0.05–0.50 crabs/trap, and the information benefit decreased at crab densities higher and lower than this range (Figure 6).

Both the joint and trap-only models produced accurate estimates of green crab density in a diverse set of

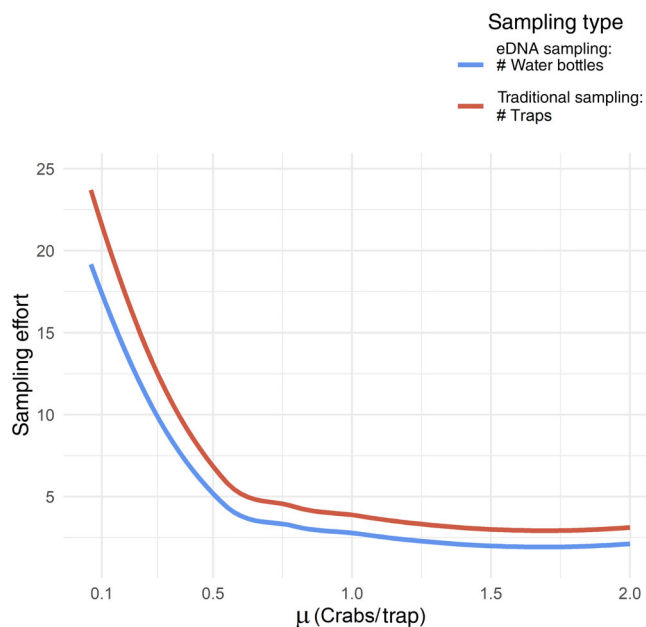


FIGURE 5 Sampling effort necessary to detect a green crab with 90% confidence. Lines designate the type of sampling effort (water bottles, traps)

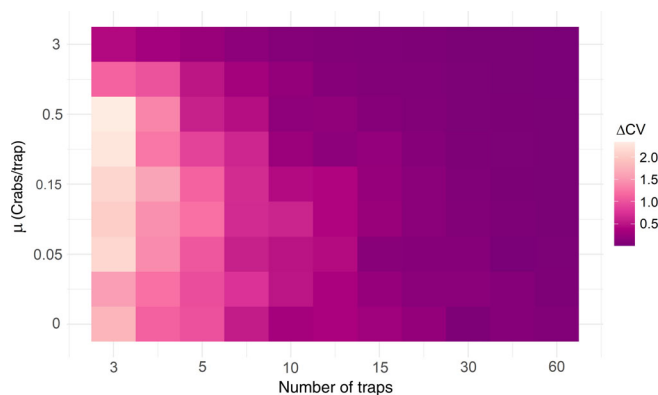


FIGURE 6 Marginal benefit of eDNA data at each simulated true crab density and trapping effort. The information benefit is represented by the difference in the coefficient of variation (ΔCV) in the posterior distributions of the estimated green crab densities between a model using only trapping information (trap-only model) and a model using both trapping and eDNA information (joint model). Each grid cell represents the mean ΔCV for all simulation scenario replicates. Both the x and y axes are presented on a non-linear scale

simulations. For scenarios in which $\mu_{\text{sim}} > 0$, 100% of simulation replicates yielded 90% credibility intervals of density estimates that contained the true green crab density, μ_{sim} . For scenarios in which $\mu_{\text{sim}} = 0$, no simulation replicates yielded 90% credibility intervals of density estimates that contained the true green crab density, μ_{sim} .

DISCUSSION

Many management and policy decisions have prominent economic and social consequences, particularly surrounding invasive or endangered species, which often occur at low densities. Finding the leading edge of an invasion front can correspondingly require government agencies and others to engage in high-cost sampling that nevertheless has little power to detect rare individuals. As eDNA comes to the forefront as a routine sampling technique that can ameliorate some of these difficulties, it is important to quantify the value of this new data stream and to adequately characterize the uncertainty associated with all kinds of environmental sampling. By jointly modeling eDNA and traditional (trap) data for the invasive European green crab, we (1) estimated the abundance of the species at its leading edge of invasion, (2) quantified uncertainty in both detection methods and showed the marginal information benefit of an eDNA data stream, and (3) offered a framework for integrating eDNA into existing data streams and survey programs.

Improving interpretation of eDNA data

Our quantitative approach builds upon previous work adapting occupancy modeling approaches to facilitate eDNA data interpretation (Griffin et al., 2019; Lahoz-Monfort et al., 2016; Pilliod et al., 2013; Schmidt et al., 2013). These previous approaches suggest that there are two classes of sites—those that are occupied and those that are not—and crucially, that the probability of detecting a species is constant within a given ecological context. This assumption can be insufficient in the context of eDNA surveys, in which local abundance can induce heterogeneity in detection probability (Altwegg & Nichols, 2019; Royle & Dorazio, 2008; Royle & Nichols, 2003). The joint model presented here uses the heterogeneity in molecular detection probability to estimate species density, rather than occupancy, and operates under the assumption that the probability of a true detection increases as species density increases.

The joint model uses observations from two sampling methods, each generated independently from a shared underlying species density. The two data streams inform one another: the combined likelihood borrows strength from the sites with greater trapping effort over the sampling period to infer detection biases across all locations and to inform species density at data-limited sites. The model also reveals the relative sensitivities of the two sampling methods and the relative information contributions of eDNA data at varying trap sampling efforts.

In practical application, environmental factors including flow rates, turbulence, temperature, water chemistry, and UV light can affect the dilution, persistence, and strength of an eDNA signal (Andruszkiewicz et al., 2017; Barnes & Turner, 2016; Deiner & Altermatt, 2014; Sansom & Sassoubre, 2017). Quantitatively modeling eDNA detections and integrating traditional and new sampling approaches help to mitigate this challenge by capturing uncertainty in how eDNA detections arise from true species presence and density.

To overcome challenges with parameter identifiability typical of hierarchical models of eDNA data (Griffin et al., 2019; Guillera-Arroita et al., 2017), the model uses a Bayesian framework and sets plausible bounds on the false-positive probability as prior information. Recognizing the tendency for Bayesian priors to induce undue influence on the model's inferences (Cressie et al., 2009; Lele & Dennis, 2009), we conducted robustness assessments to investigate the effect of prior assumptions. We found that our inferences are largely robust to prior specification (Appendix S3: Figures S3, S4); although at certain sites with a low trapping effort, there is not enough information in the data to limit the influence of the specified false-positive probability prior (Appendix S3: Figure S3).

Importantly, the joint model's results can aid appropriate management responses after a molecular detection. In management contexts, positive eDNA detections are commonly used to prompt non-molecular sampling for corroboration (Sepulveda, Hutchins, et al., 2020), as shown in the Great Lakes invasive carp eDNA surveillance program (Woldt et al., 2020). However, after a positive eDNA detection, managers must decide how intense (and therefore expensive) the management response must be, and it is often difficult or impossible to confirm a species' absence with traditional methods (Morrison et al., 2007; Russell et al., 2017). Quantifying uncertainty for any given detection method encourages agencies to explicitly set tolerable risk levels for the presence of a target species.

The results of the joint model offer a framework for inferring a species density threshold, μ_{critical} , at which a molecular detection is as likely to be a false-positive detection as a true-positive detection. This value provides an opportunity to investigate the probability that an eDNA detection reflects the true presence of a species. For example, two sites yielded one positive qPCR detection each, yet the median estimated crab densities were very near zero (0.0013 and 6.5e-7 crabs/trap at JIM creek and KVI Beach, respectively). Given the combination of molecular and trapping data in hand, these detections are as likely to be false positives as true positives. Further detections by either method would change this interpretation, but the ability to quantify uncertainty in this way is valuable.

Quantifying the practical value of eDNA information

Our framework offers a way to fold genetic surveys into existing management practices, therefore moving the contribution of eDNA data to management practices from “potential” value to practical value. For the specific example of the green crab assay, the marginal benefit of eDNA data—measured as increases in the precision of species density estimates upon the addition of eDNA data—is highest at sites with low trapping effort, and this information benefit increases exponentially as traditional trapping effort decreases (Figures 4 and 6). Therefore data-limited applications particularly stand to gain from molecular surveys.

Simulations identified a parameter space, or a combination of true green crab density and existing trapping effort, in which the marginal benefit of eDNA information is highest. These simulations suggested that eDNA sampling is most useful at low trapping efforts and a green crab density of ~ 0.05 – 0.50 crabs/trap, a sampling combination in which a true molecular detection is probable, and a detection through baited trapping is unlikely. Importantly, as the true green crab density fell below ~ 0.05 crabs/trap (for which the true detection rate $[p_{11}]$ falls below the false-detection rate $[p_{10}]$), the information benefit of eDNA data decreased. Previous work faces similar challenges in detecting green crab eDNA at low densities with existing molecular assays, and suggested that a different assay was more sensitive during green crab spawning periods (Crane et al., 2021).

Therefore, the joint model not only indicates when the marginal benefit of eDNA sampling is highest, but also when marginal benefit of eDNA is negligible, which is valuable information for allocating limited monitoring resources. We find that eDNA sampling is unlikely to improve management at locations with high trapping effort or a high species density (Figures 4, 6), situations in which managers essentially already have the information they seek. For example, eDNA samples were collected in Dungeness National Wildlife Refuge, an area rich in marine life that contains one of the world’s longest sand spits. The watershed in this area is also home of the Jamestown S’Klallam Tribe, providing abundant resources from its tidelands and marine waters (Jamestown S’Klallam Tribe, 2007). The US Department of Fish and Wildlife implements an intense removal trapping procedure in the national refuge. In 2020 in Graveyard Spit Channel (GSC), 1369 traps were set, and three green crabs were recovered. The combination of high trapping effort and inferred crab densities well below μ_{critical} means that eDNA sampling would be unlikely to improve the existing survey estimates at this site.

The veracity of negative results are often of equal importance as confirmation of positive detections, and eDNA sampling has previously been used in species eradication campaigns (Carim et al., 2020; Davison et al., 2019; Larson et al., 2020). However, the sensitivity of the assay tested here illustrates a case in which the similar rates of detection between traditional and molecular sampling mean that it is difficult to confirm a species’ absence with either method (Morrison et al., 2007; Russell et al., 2017).

Although costs of eDNA-based surveys tend to compare favorably with those of traditional capture-based methods (Biggs et al., 2015; Sigsgaard et al., 2015), future work should identify the survey regime that maximizes detection probability under a fixed budget. Previous cost–efficiency analyses find that eDNA is less cost efficient at low sample numbers, as costs associated with initial investments in reagents and supplies for laboratory analysis are high (Smart et al., 2016). However, because traditional sampling requires repeat visits and more time- and labor-intensive sampling efforts, eDNA sampling has lower field labor and transportation costs and can become more cost effective compared with traditional sampling when examining a large number of sites (Khalsa et al., 2020). Such cost comparisons are critical when identifying the optimal allocation of survey effort to maximize detection, and future cost–efficiency inquiries should consider the role of site-specific characteristics that affect the relative costs of sampling methods.

Increasing certainty at the green crab’s invasion front

By contrast, sites with low trapping effort are likely to benefit from the additional information that eDNA offers. In the context of green crab, the most notable example of eDNA data’s value at the invasion front is the estimation of a relatively high green crab density at a site well beyond green crab’s previously known distribution (Figures 2 and 3; Appendix S4: Table S4). By interpreting the pattern of eDNA signals, the joint model indicates green crab eDNA presence with relatively high certainty at Raab’s Lagoon (RAA) on Vashon Island, suggesting that the local species density is perhaps low and previously undetectable using traditional monitoring methods implemented at a low effort. We estimate the green crab density at Raab’s Lagoon—one of the sites beyond the previously known invasion front—to be 0.16 crabs/trap ($4.0e-61$, 0.61 90%CrI). The probability that the green crab density is greater than the median μ_{critical} , or the crab density at which the associated true probability of detection equals the estimated false-positive probability,

is 0.64 (Figure 2; Appendix S4: Table S4). This finding is consistent with studies showing that sufficient eDNA sampling applied across large geographic areas can reveal unexpected patterns and new occurrences of species missed by traditional approaches (Mckelvey et al., 2016; Tucker et al., 2016), and the Bayesian modeling framework allows these statements of new occurrences to be tempered by quantified uncertainty (Hobbs & Hooten, 2015). However, the model treats molecular detections and trapped adults as conceptually equivalent, with a joint estimate of species “density” in units of crabs per trap. This is a somewhat imprecise description insofar as molecular detections potentially include larval and dead individuals. Depending upon management priorities, detections of larval or dead individuals may (or may not) rise to the level of importance of live adult detections. Indeed, results of trapping at RAA and KVI in July 2021 suggested that these molecular detections may have been larvae and, to date, no adults have been captured at RAA, KVI, or neighboring sites in the South Sound through trapping efforts by the Washington Sea Grant (WSG) Crab Team, WDFW, and partners.

False positives and false negatives

The fear of false-positive detections is often cited as the primary hurdle for adopting eDNA approaches for species monitoring (Jerde, 2019). However, the term “false positive” can be misleading in the eDNA context (Darling et al., 2021): different mechanisms contribute to false-positive errors, and we can distinguish between errant detection in an individual sample vs. errant detection at an unoccupied site (Chambert et al., 2015; Darling et al., 2021; Guillera-Aroita et al., 2017). Our model explicitly estimates a molecular false-positive probability, which incorporates both the probability of a false-positive sample and the probability of a false-positive site through information included in the parameter’s prior distribution and unambiguous presence sites with a high trapping intensity. In this study, however, field negative controls (clean water collected using the same protocol and equipment as field samples) were not collected at all sites, and these negative controls are critical for detecting contamination and informing the false-positive probability (Goldberg et al., 2016). Future work should include separate negative controls at each stage of the eDNA sampling process to help to identify sources of contamination when it occurs and to properly model the false-positive probability.

Notably, our false-positive probability does not include scenarios in which we detect nonviable

organisms or larval individuals: these are true-positive detections of eDNA present at the sampled site. In a management context, molecular detection of larvae alone does not necessarily indicate a high probability of invasion. However, with an invasive species with high larval-dispersal potential, larval detection beyond the known invasion front has high value for management planning and can be used to prioritize areas for assessment and prospecting.

False-negative detections similarly erode an assay’s usefulness in eDNA work, as in every other sampling method (Goldberg et al., 2016; Hunter et al., 2019). PCR inhibition can mask even high eDNA copy numbers and thereby profoundly affects molecular detection estimates (Jane et al., 2015). For example, DNA extracted from turbid water often contains humic acid and tannin compounds, created through non-enzymatic decay of the organic material, and these compounds can inactivate DNA polymerase and inhibit the PCR amplification process, reducing PCR efficiency or causing PCR failure (Albers et al., 2013; Goldberg et al., 2016). No samples included in this analysis were substantially inhibited, but it remains important to test for inhibition to guard against an inflated false-negative rate in any molecular assay.

CONCLUSION

Given the limited resources available to State and tribal government agencies charged with controlling invasive species, there is significant value in identifying and implementing optimal invasive species management strategies. Applications of eDNA methods have represented some of the most significant advances in invasive species surveillance in the recent decade, yet uncertainty inherent in eDNA sampling means that managers are often hesitant to direct management actions based solely on molecular evidence. Although previous work has identified the potential for DNA-based methods to amplify the uncertainty already associated with invasive species risk assessment (Benke et al., 2007; Darling & Mahon, 2011; Sikder et al., 2006), here we demonstrate that eDNA increases certainty at data-limited locations, and we highlight scenarios under which eDNA sampling is most useful in the context of green crab management. The value of eDNA sampling at low species densities and data-limited areas has largely been discussed (Crookes et al., 2020; Suarez-Menendez et al., 2020; Villacorta-Rath et al., 2020), but here we provide a means to formally quantify this value.

The joint model aids eDNA data interpretation and contributes to a growing body of analyses providing frameworks for inferring confidence in patterns of eDNA

detections (Furlan et al., 2016; Guillera-Aroita et al., 2017; Lahoz-Monfort et al., 2016). This approach also offers a means to combine eDNA and traditional monitoring methods to make more reliable inferences about data-limited sites and provides reassurance to managers and other stakeholders wary of adopting a new technology. Whereas environmental DNA methods can support detection of invasive species at low abundances, improved statistical methods to interpret patterns of environmental DNA detections can empower informed management responses.

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CONFLICT OF INTEREST


The authors declare no conflict of interest.

DATA AVAILABILITY STATEMENT

All data and statistical code (Keller, 2021) are available in Figshare at <https://doi.org/10.6084/m9.figshare.15117102.v2>.

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